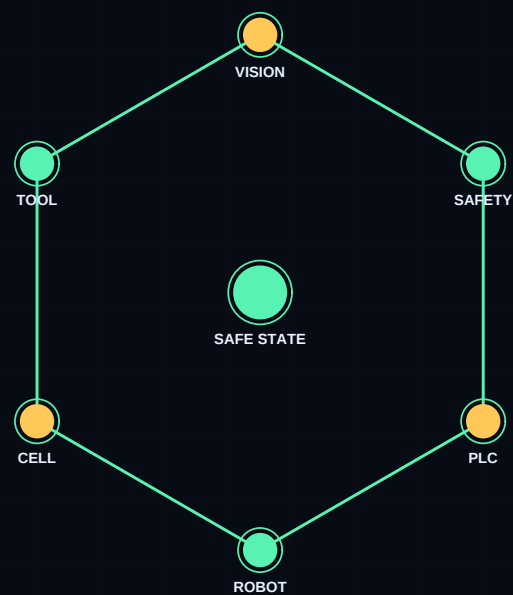
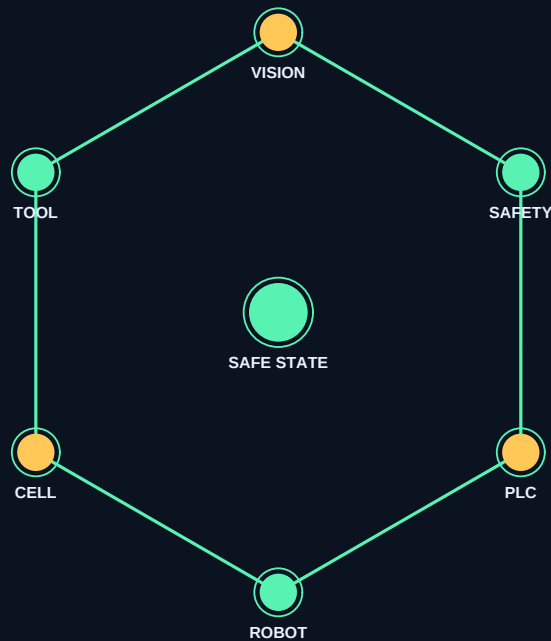


Industrial Robotics, Collaborative Robot, and Cell Integration Standard



Architecture & Assurance Map

A compact reasoning model for implementation, assessment, and evidence review.



OPERATING POSITION

Physical AI must remain bounded by safety, authority, uncertainty, and recoverability.

EVIDENCE PATH

sense -> interpret -> plan -> authorize -> act -> observe -> recover

READINESS SIGNALS

hazard controls, human override, perception confidence, geofence, fail-safe state

PERMANENT PUBLICATION IDENTITY

Industrial Robotics, Collaborative Robot, and Cell Integration Standard			DOCUMENT ID MYTHOS-ROB-0003 VERSION 1.0.0-candidate STATUS Candidate Standard PUBLISHER Mythos Systems PUBLICATION DATE 2026-07-24 SCHEDULED REVIEW 2027-01-24 CLASSIFICATION Public
18 ATOMIC CRITERIA	6 ASSURANCE VIEWS	4 IMPLEMENTATION PROFILES	1 PERMANENT IDENTITY

Publication doctrine. This publication establishes durable requirements for its defined scope. Interpretation must preserve the permanent document identity, required evidence, controlled exceptions, source currency, and formal revision history.

EMERGING TECHNOLOGY AND ASSURANCE TOPOLOGY

Robotics and Autonomous Systems

A trustworthy industrial robotics and collaborative cells program is a governed path from research claim through baseline, experiment, safety and security challenge, transition decision, bounded operation, and preserved evidence.

CLASSIFY

Separate established practice, candidate standard, reproduced result, vendor claim, implementation hypothesis, and open research.

EXPERIMENT

Declare baseline, configuration, uncertainty, scenario coverage, stop conditions, and independent reproduction before conclusions.

CONSTRAIN

Identity, policy, safety envelopes, physical boundaries, cryptographic authority, and human intervention limit consequence.

TRANSITION

Adoption, pilot, production, rollback, supplier exit, lifecycle, and retirement decisions remain evidence-bearing and reversible.

EVIDENCE - BOUND TRANSITION FLOW



No novelty claim becomes an operational claim without reproduced evidence and an explicit authority decision

INTERPRETATION AND ASSURANCE

How to apply this publication

Normative intent

Requirements define outcomes and constraints. Implementations may vary, but evidence must demonstrate equivalent control.

Evidence over assertion

Vendor documentation and design intent are not equivalent to reproduced behavior. Record evidence grade and uncertainty.

Risk-proportional depth

Higher consequence, autonomy, sensitivity, and irreversibility require stronger isolation, review, verification, and recovery.

Controlled exception

Exceptions require an owner, rationale, compensating control, residual-risk acceptance, expiration, and reevaluation trigger.

Normalized assessment scale

0 ABSENT	1 AD HOC	2 PARTIAL	3 OPERATIONAL	4 ADVANCED	5 LEADING
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A numeric score must never hide a failed mandatory gate, missing evidence, untested workload, or unacceptable residual risk.

INTERACTIVE NAVIGATION

Contents

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Navigation doctrine

Bookmarks and internal links are conveniences. Permanent document identity, criterion identifiers, evidence references, and revision history remain authoritative.

MYTHOS-ROB-0003 / ROBOTICS AND AUTONOMY

0. Executive Mandate

Research value, transition discipline, and non-negotiable evidence boundaries

MANDATE

Organizations evaluating industrial robotics and collaborative cells **MUST** separate research from operational authority, establish a reproducible baseline, constrain safety and security consequence, disclose uncertainty, and require a documented transition or rejection decision.

Required outcomes

- Establish a durable, product-neutral evidence system for industrial robotics and collaborative cells.
- Prevent novelty, investment, vendor prestige, roadmap language, or laboratory success from substituting for operational proof.
- Require representative performance, adversarial, failure, recovery, safety, privacy, and lifecycle evidence.
- Keep pilots bounded by identity, authority, environment, duration, budget, stop conditions, and rollback.
- Preserve rejected alternatives, limitations, residual risk, source currency, and reassessment triggers.

Decision boundary: conformance supports a bounded engineering assurance position. It does not prove scientific consensus, regulatory approval, universal safety, quantum advantage, cryptographic perfection, autonomous competence, or commercial viability.

MYTHOS-ROB-0003 / ROBOTICS AND AUTONOMY

1. Scope and Applicability

Research, pilot, transition, operational, and retirement boundaries

IN SCOPE

- Research, architecture, acquisition, experiment, pilot, transition, operation, and retirement of industrial robotics and collaborative cells.
- Hardware, software, models, data, protocols, facilities, people, suppliers, providers, physical processes, and evidence.
- Laboratory, simulation, testbed, shadow, pilot, canary, production, and field deployment states.
- Claims, benchmarks, uncertainty, safety, security, privacy, economics, interoperability, support, and exit.

OUT OF SCOPE

- Scientific truth inferred from a single benchmark, simulation, provider, hardware generation, or laboratory configuration.
- Safety, regulatory, export, spectrum, airspace, clinical, cryptographic, or standards approval not granted by the responsible authority.
- Roadmap forecasts, token price, patent counts, press releases, or investment treated as engineering evidence.
- Hidden production use of research components outside the declared transition and assurance boundary.

Applicability triggers

- The capability is novel, rapidly changing, weakly standardized, difficult to reproduce, or dependent on immature suppliers.
- A claim concerns safety, security, privacy, physical action, critical infrastructure, cryptographic trust, or consequential autonomy.
- The system requires specialized facilities, scarce hardware, spectrum, foundry, cryogenic, optical, robotics, or field-test dependencies.
- Failure or lock-in may create long-lived data, capital, infrastructure, workforce, or regulatory consequences.
- A research component is proposed for pilot, customer, production, public, or externally relied-upon use.

MYTHOS-ROB-0003 / ROBOTICS AND AUTONOMY

2. Definitions and Taxonomy

Controlled language for architecture, governance, and assessment

AUTHORITY

The right to approve, deny, constrain, or execute an action. Model output is not authority.

EVIDENCE

A reproducible source, trace, measurement, test, record, signed artifact, or documented observation supporting a claim.

ASSURANCE VIEW

A defined perspective such as governance, architecture, security, operations, privacy, or human oversight.

ATOMIC CRITERION

A uniquely identified requirement that can be assessed, evidenced, excepted, and revised independently.

IMPLEMENTATION PROFILE

A risk-proportional set of required depth, evidence, and gates for a class of use.

CONTROLLED EXCEPTION

A time-bounded deviation with owner, rationale, compensating control, residual risk, expiration, and review trigger.

DETERMINISTIC MECHANISM

A component whose inputs, policy, state transition, and side effects can be constrained and verified.

SOURCE AUTHORITY

The documented basis for treating a source as reliable for a defined claim, context, jurisdiction, and time.

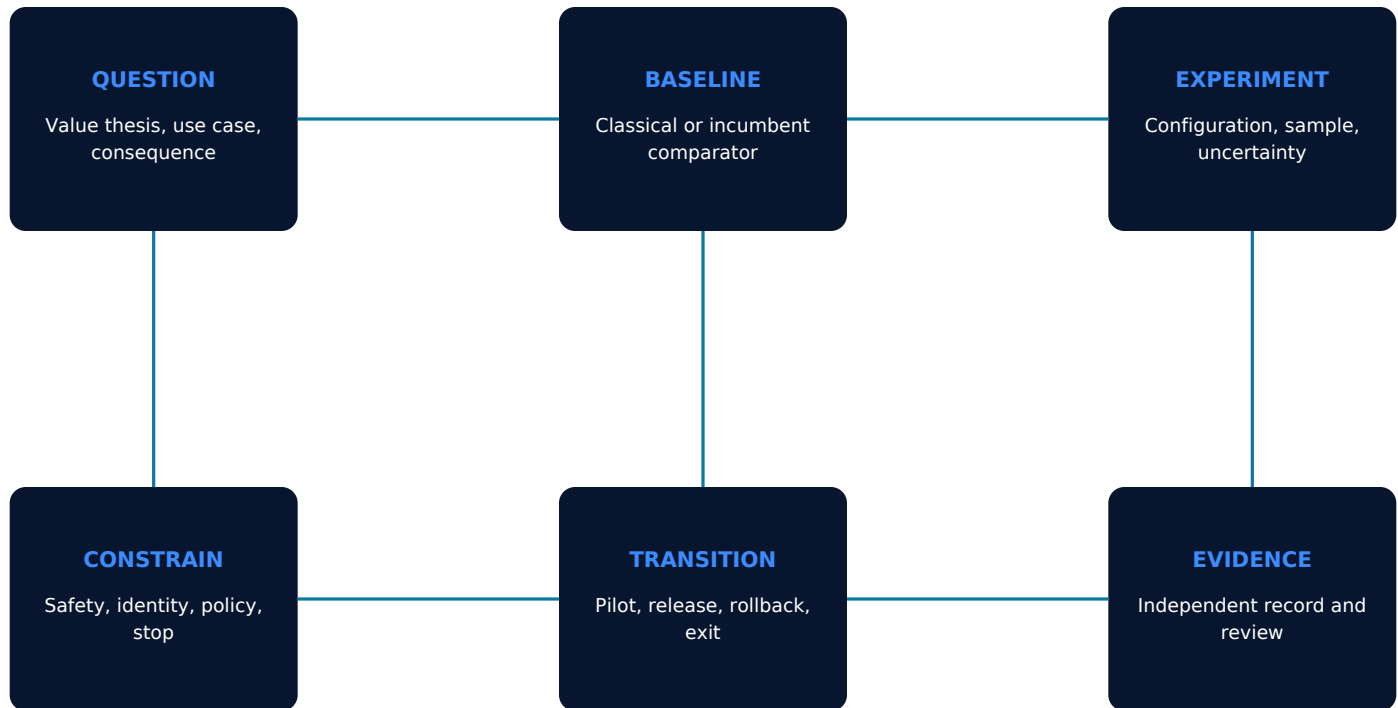
REASSESSMENT TRIGGER

A change, incident, drift signal, dependency revision, or time boundary requiring renewed evaluation.

MYTHOS-ROB-0003 / ROBOTICS AND AUTONOMY

3. Architecture and Trust Model

Separation of research, authority, physical systems, runtime, and evidence



Mandatory trust boundaries

- Research systems **MUST NOT** inherit production identity, secrets, authority, data, networks, or physical control by convenience.
- Claims **MUST** retain the exact hardware, software, model, protocol, calibration, environment, workload, and observation boundary.
- Safety, cryptographic, physical, spectrum, autonomy, and human-intervention constraints **MUST** remain independently enforceable.
- Transition **MUST** have a named decision authority, acceptance criteria, monitored pilot, rollback, supplier exit, and retirement path.
- Evidence **MUST** remain reviewable when a vendor, cloud, token network, laboratory, model, robot, or quantum backend is unavailable.

MYTHOS-ROB-0003 / ROBOTICS AND AUTONOMY

4. Governance and Accountability

Decision rights, separation of duties, and lifecycle ownership

ACCOUNTABLE OWNER

Accepts scope, risk tolerance, funding, and residual risk.

SYSTEM OWNER

Maintains architecture, inventory, operating boundaries, and change control.

SECURITY / PRIVACY

Defines threat, identity, data, isolation, monitoring, and incident requirements.

EVALUATION AUTHORITY

Designs representative tests, gates releases, and preserves reproducibility.

OPERATIONS

Maintains availability, rollback, recovery, evidence, and incident handling.

HUMAN OVERSIGHT

Reviews consequential decisions, exceptions, disputed outcomes, and harm signals.

DECISION PRINCIPLE

No single actor should be able to define the objective, grant authority, execute the consequential action, suppress evidence, and approve the result. Separation must be technical where consequence requires it.

MYTHOS-ROB-0003 / ROBOTICS AND AUTONOMY

5. Normative Control System

Atomic criteria 01-04 of 18

MYTHOS-ROB-0003-C01 Robot and Cell Integration Responsibility

The organization **MUST** define, implement, verify, and maintain robot and cell integration responsibility for the declared industrial robotics and collaborative cells boundary. The record **MUST** identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence **MUST** be testable.

MINIMUM EVIDENCE robot and application boundary; ODD; hazard analysis; safety and cybersecurity ownership

MYTHOS-ROB-0003-C02 Machine, Process, Material, and Tool Hazard Inventory

The organization **MUST** define, implement, verify, and maintain machine, process, material, and tool hazard inventory for the declared industrial robotics and collaborative cells boundary. The record **MUST** identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence **MUST** be testable.

MINIMUM EVIDENCE safety function validation; stop, intervention, safe-state, and stored-energy tests

MYTHOS-ROB-0003-C03 Layout, Access, Guarding, and Safeguarding

The organization **MUST** define, implement, verify, and maintain layout, access, guarding, and safeguarding for the declared industrial robotics and collaborative cells boundary. The record **MUST** identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence **MUST** be testable.

MINIMUM EVIDENCE sensor calibration; dataset provenance; simulation validity; scenario and field-test coverage

MYTHOS-ROB-0003-C04 Collaborative Application and Contact-Risk Assessment

The organization **MUST** define, implement, verify, and maintain collaborative application and contact-risk assessment for the declared industrial robotics and collaborative cells boundary. The record **MUST** identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence **MUST** be testable.

MINIMUM EVIDENCE identity, command, network, remote-access, software, firmware, model, and update evidence

MYTHOS-ROB-0003 / ROBOTICS AND AUTONOMY

5. Normative Control System

Atomic criteria 05-08 of 18

MYTHOS-ROB-0003-C05 Speed and Separation Monitoring

The organization MUST define, implement, verify, and maintain speed and separation monitoring for the declared industrial robotics and collaborative cells boundary. The record MUST identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence MUST be testable.

MINIMUM EVIDENCE normal, degraded, adversarial, lost-link, lost-localization, and recovery test results

MYTHOS-ROB-0003-C06 Power and Force Limiting

The organization MUST define, implement, verify, and maintain power and force limiting for the declared industrial robotics and collaborative cells boundary. The record MUST identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence MUST be testable.

MINIMUM EVIDENCE operator training; human factors; takeover, rescue, maintenance, and incident procedure

MYTHOS-ROB-0003-C07 Hand Guiding and Monitored Stop

The organization MUST define, implement, verify, and maintain hand guiding and monitored stop for the declared industrial robotics and collaborative cells boundary. The record MUST identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence MUST be testable.

MINIMUM EVIDENCE fleet telemetry, mission record, decision trace, near-miss, maintenance, and change history

MYTHOS-ROB-0003-C08 Safety-Rated Control, Interlock, and Reset Logic

The organization MUST define, implement, verify, and maintain safety-rated control, interlock, and reset logic for the declared industrial robotics and collaborative cells boundary. The record MUST identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence MUST be testable.

MINIMUM EVIDENCE acceptance, revalidation, regulatory review, residual risk, retirement, and evidence archive

MYTHOS-ROB-0003 / ROBOTICS AND AUTONOMY

5. Normative Control System

Atomic criteria 09-12 of 18

MYTHOS-ROB-0003-C09

Tool Change, End-Effector, Fixture, and Payload Control

The organization **MUST** define, implement, verify, and maintain tool change, end-effector, fixture, and payload control for the declared industrial robotics and collaborative cells boundary. The record **MUST** identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence **MUST** be testable.

MINIMUM EVIDENCE robot and application boundary; ODD; hazard analysis; safety and cybersecurity ownership

MYTHOS-ROB-0003-C10

Process-Specific Heat, Fume, Pressure, Sharp, and Chemical Risk

The organization **MUST** define, implement, verify, and maintain process-specific heat, fume, pressure, sharp, and chemical risk for the declared industrial robotics and collaborative cells boundary. The record **MUST** identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence **MUST** be testable.

MINIMUM EVIDENCE safety function validation; stop, intervention, safe-state, and stored-energy tests

MYTHOS-ROB-0003-C11

Teaching, Programming, Maintenance, and Bypass Modes

The organization **MUST** define, implement, verify, and maintain teaching, programming, maintenance, and bypass modes for the declared industrial robotics and collaborative cells boundary. The record **MUST** identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence **MUST** be testable.

MINIMUM EVIDENCE sensor calibration; dataset provenance; simulation validity; scenario and field-test coverage

MYTHOS-ROB-0003-C12

Network, Remote Support, and Engineering Access

The organization **MUST** define, implement, verify, and maintain network, remote support, and engineering access for the declared industrial robotics and collaborative cells boundary. The record **MUST** identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence **MUST** be testable.

MINIMUM EVIDENCE identity, command, network, remote-access, software, firmware, model, and update evidence

MYTHOS-ROB-0003 / ROBOTICS AND AUTONOMY

5. Normative Control System

Atomic criteria 13-15 of 18

MYTHOS-ROB-0003-C13**Commissioning, Validation, and Acceptance Test**

The organization **MUST** define, implement, verify, and maintain commissioning, validation, and acceptance test for the declared industrial robotics and collaborative cells boundary. The record **MUST** identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence **MUST** be testable.

MINIMUM EVIDENCE normal, degraded, adversarial, lost-link, lost-localization, and recovery test results

MYTHOS-ROB-0003-C14**Production Quality, Cycle, Fault, and Safety Monitoring**

The organization **MUST** define, implement, verify, and maintain production quality, cycle, fault, and safety monitoring for the declared industrial robotics and collaborative cells boundary. The record **MUST** identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence **MUST** be testable.

MINIMUM EVIDENCE operator training; human factors; takeover, rescue, maintenance, and incident procedure

MYTHOS-ROB-0003-C15**Operator Training, Procedure, and Competency**

The organization **MUST** define, implement, verify, and maintain operator training, procedure, and competency for the declared industrial robotics and collaborative cells boundary. The record **MUST** identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence **MUST** be testable.

MINIMUM EVIDENCE fleet telemetry, mission record, decision trace, near-miss, maintenance, and change history

MYTHOS-ROB-0003 / ROBOTICS AND AUTONOMY

5. Normative Control System

Atomic criteria 16-18 of 18

MYTHOS-ROB-0003-C16**Modification, Relocation, and Revalidation**

The organization **MUST** define, implement, verify, and maintain modification, relocation, and revalidation for the declared industrial robotics and collaborative cells boundary. The record **MUST** identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence **MUST** be testable.

MINIMUM EVIDENCE acceptance, revalidation, regulatory review, residual risk, retirement, and evidence archive

MYTHOS-ROB-0003-C17**Rescue, Recovery, Lockout, and Stored Energy**

The organization **MUST** define, implement, verify, and maintain rescue, recovery, lockout, and stored energy for the declared industrial robotics and collaborative cells boundary. The record **MUST** identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence **MUST** be testable.

MINIMUM EVIDENCE robot and application boundary; ODD; hazard analysis; safety and cybersecurity ownership

MYTHOS-ROB-0003-C18**Lifecycle Evidence and Periodic Inspection**

The organization **MUST** define, implement, verify, and maintain lifecycle evidence and periodic inspection for the declared industrial robotics and collaborative cells boundary. The record **MUST** identify accountable ownership, evidence state, exact configuration, assumptions, affected people and systems, failure and recovery behavior, uncertainty, transition authority, and reassessment triggers. The operational design domain, hazard controls, human intervention, safe state, physical consequence, field validation, and incident evidence **MUST** be testable.

MINIMUM EVIDENCE safety function validation; stop, intervention, safe-state, and stored-energy tests

MYTHOS-ROB-0003 / ROBOTICS AND AUTONOMY

6. Evidence and Assessment

Reproduce, compare, challenge, observe, and trace

EXAMINE

Research papers, standards, designs, bills of material, protocols, source, models, data, calibration, configurations, contracts, and claims.

REPRODUCE

Repeat the experiment or assessment with captured versions, seeds, parameters, environment, uncertainty, and acceptance criteria.

COMPARE

Use an honest incumbent, classical, manual, or alternative baseline with equivalent outcome, data, scale, and resource accounting.

CHALLENGE

Apply adversarial input, environmental variation, dependency loss, fault injection, safety cases, security tests, and boundary conditions.

OBSERVE

Measure field or production-like quality, latency, energy, drift, physical behavior, interventions, failures, maintenance, and user impact.

TRACE

Link claim, authority, experiment, configuration, evidence, decision, pilot, change, incident, rollback, and reassessment.

Evidence grades

A

Independently reproduced, current, representative, uncertainty-bounded, integrity-protected, and operationally relevant.

B

Reproduced by the implementing organization with strong provenance, comparator, challenge, and declared limitations.

C

Partial, laboratory-only, simulation-heavy, inherited, or indirect evidence with material uncertainty and dependencies.

D

Roadmap, assertion, demonstration, benchmark excerpt, patent, token metric, press release, or vendor statement without...

MYTHOS-ROB-0003 / ROBOTICS AND AUTONOMY

7. Assurance Views

Six perspectives required for a complete assurance claim

GOVERNANCE

Ownership, purpose, risk tolerance, policy, exception, and decision rights.

ARCHITECTURE

Boundaries, dependencies, failure modes, state, data flow, and portability.

SECURITY

Identity, authorization, isolation, secrets, abuse resistance, and incident response.

OPERATIONS

Reliability, performance, cost, observability, change, recovery, and support.

PRIVACY / RIGHTS

Purpose limitation, minimization, consent, access, correction, deletion, and egress.

HUMAN / SOCIETAL

Usability, accessibility, disclosure, contestability, impact, and human control.

Conformance requires a defensible position across every applicable view. A strong aggregate score cannot compensate for an unowned system, a failed mandatory gate, untested recovery, or evidence below the accepted grade.

MYTHOS-ROB-0003 / ROBOTICS AND AUTONOMY

7.2 Evaluation Metrics and Decision Gates

Measures expose utility, uncertainty, safety, physical limits, transition cost, and lifecycle burden

UTILITY

Task outcome, comparator delta, coverage, quality, accuracy, mission success, and stakeholder value.

UNCERTAINTY

Confidence, calibration, variance, sample coverage, reproducibility, sensitivity, and unresolved assumptions.

PERFORMANCE

Latency, throughput, fidelity, range, precision, bandwidth, scale, density, and availability.

SAFETY / SECURITY

Hazard exposure, unsafe action, exploitability, spoofing, physical consequence, intervention, and containment.

RESOURCE

Energy, power, cooling, spectrum, shots, qubits, memory, materials, facility, operator, and maintenance demand.

MATURITY

Standards state, supply chain, interoperability, tooling, skills, support, qualification, and lifecycle readiness.

ECONOMICS

Acquisition, operation, provider, token, facility, migration, insurance, support, and opportunity cost.

TRANSITION

Pilot escape, rollback time, incumbent fallback, portability, lock-in, retirement, and evidence completeness.

Decision gate: thresholds **MUST** be declared before assessment, include an incumbent baseline and uncertainty statement, and identify any safety, security, cryptographic, physical, reproducibility, or rollback failure that blocks transition.

MYTHOS-ROB-0003 / ROBOTICS AND AUTONOMY

8. Failure Modes and Adversarial Scenarios

Challenge assumptions before the system is trusted with consequential work

UNSAFE AUTONOMY

The robot acts outside its operational design domain or safety envelope.

REQUIRED: PREVENT | DETECT | CONTAIN | RECOVER | EVIDENCE

PERCEPTION COLLAPSE

Occlusion, weather, spoofing, drift, calibration, or domain shift produces hazardous state estimates.

REQUIRED: PREVENT | DETECT | CONTAIN | RECOVER | EVIDENCE

HUMAN INTERVENTION FAILURE

Operators cannot understand, stop, take over, or recover the system in time.

REQUIRED: PREVENT | DETECT | CONTAIN | RECOVER | EVIDENCE

CYBER-PHYSICAL COMMAND ABUSE

Compromised identity, network, software, model, or tool issues unsafe motion or process actions.

REQUIRED: PREVENT | DETECT | CONTAIN | RECOVER | EVIDENCE

FLEET-CORRELATED FAILURE

A map, model, update, scheduler, battery, cloud, or communications dependency affects many robots at once.

REQUIRED: PREVENT | DETECT | CONTAIN | RECOVER | EVIDENCE

LEARNING REGRESSION

A model or skill update degrades safety, task quality, fairness, explainability, or recovery behavior.

REQUIRED: PREVENT | DETECT | CONTAIN | RECOVER | EVIDENCE

Adversarial testing MUST protect people and production systems. Use isolated environments, synthetic or minimized data, bounded authority, kill switches, explicit legal and ethical review, and documented stop conditions.

9. Implementation Profiles

Risk-proportional implementation without weakening mandatory boundaries

FOUNDATIONAL TYPICAL SCOPE Low consequence, limited autonomy, non-sensitive data, reversible outputs. MINIMUM DEPTH Named owner; inventory; basic evaluation; access control; logging; rollback; annual review.	ADVANCED TYPICAL SCOPE Business-critical workflow, sensitive data, multiple tools or providers, moderate autonomy. MINIMUM DEPTH Formal threat model; representative evaluation; approval gates; isolated execution; tested recovery; quarterly review.	HIGH ASSURANCE TYPICAL SCOPE Safety, security, regulated, financial, identity, or broadly consequential use. MINIMUM DEPTH Independent challenge; strongest identity; deterministic enforcement; comprehensive evidence; canary release; continuous monitoring.
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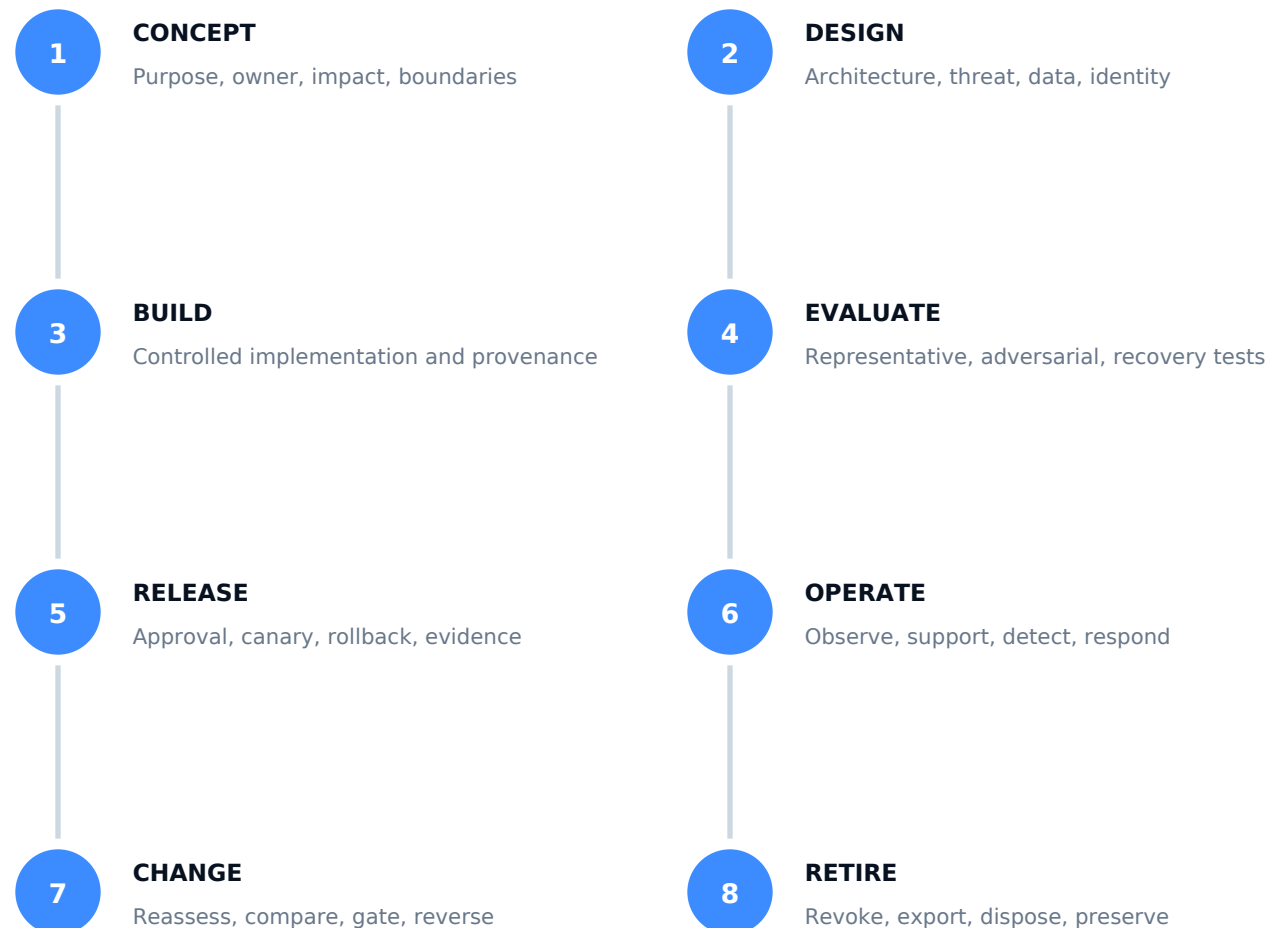
Profile selection rule

Choose the highest profile triggered by consequence, autonomy, sensitivity, scale, irreversibility, external dependency, or inability to rapidly detect and recover. Tailoring may strengthen controls; it may not erase a mandatory gate without a controlled exception.

MYTHOS-ROB-0003 / ROBOTICS AND AUTONOMY

9.2 Operational Lifecycle

Evidence-bearing operation from concept through retirement



LIFECYCLE INVARIANT

Every stage **MUST** leave sufficient evidence for the next authority to understand what was intended, what changed, what was tested, what failed, what was accepted, what remains uncertain, and how to recover or exit.

MYTHOS-ROB-0003 / ROBOTICS AND AUTONOMY

10. Adoption Roadmap

A sequenced path from uncontrolled capability to evidence-bearing operation

0-30 DAYS**Establish ownership and truth**

Inventory systems and dependencies; classify risk; freeze unsupported claims; identify immediate privilege, data, and evidence gaps.

31-90 DAYS**Create enforceable boundaries**

Define policy; isolate execution; implement identity and approval gates; establish representative evaluation and baseline telemetry.

3-6 MONTHS**Prove recovery and operating control**

Exercise failure, rollback, revocation, incident, provider exit, and state-recovery scenarios; mature evidence packaging.

6-12 MONTHS**Scale assurance**

Automate control checks; expand workload coverage; independent challenge; portfolio metrics; controlled exception expiry; continuous reassessment.

Adoption is complete only when operating evidence demonstrates the selected profile in the actual deployment context. Documentation alone is not conformance.

MYTHOS-ROB-0003 / ROBOTICS AND AUTONOMY

10.2 Conformance and Exception Statement

What an assurance claim must contain

SYSTEM / SERVICE

Named, versioned capability and deployment boundary.

PROFILE

Foundational, Advanced, or High Assurance with trigger rationale.

SCOPE

Workloads, users, data, tools, regions, providers, and exclusions.

CRITERIA

Pass, partial, fail, not applicable, and exception status for every criterion.

EVIDENCE

Artifact references, evidence grade, date, environment, and reproducibility.

LIMITATIONS

Known failure modes, unsupported workloads, uncertainty, and residual risk.

EXCEPTIONS

Owner, rationale, compensating control, expiration, and approval.

VALIDITY

Assessment date, change boundary, review date, and reassessment triggers.

Prohibited claim: “compliant” without the named scope, profile, evidence date, limitations, exceptions, and authority accepting residual risk.

11. Source Authority and Reference Register

Primary sources informing interpretation; verify current status at assessment time

NIST CSF 2.0

Cybersecurity Framework 2.0

<https://doi.org/10.6028/NIST.CSWP.29>

Enterprise governance and cybersecurity outcome framework.

ISO 13482

Robots and Robotic Devices - Safety Requirements for Personal Care Robots

<https://www.iso.org/standard/53820.html>

Safety framework for service and personal-care robot classes.

NIST SP 800-53 Rev. 5

Security and Privacy Controls for Information Systems and Organizations

<https://doi.org/10.6028/NIST.SP.800-53r5>

Broad organizational control baseline for technology systems and services.

NIST AI RMF 1.0

Artificial Intelligence Risk Management Framework

<https://doi.org/10.6028/NIST.AI.100-1>

Risk management structure for trustworthy AI capabilities used in autonomous systems.

ISO 10218-1:2025

Robotics - Safety Requirements - Industrial Robots

<https://www.iso.org/standard/73933.html>

Current industrial robot design and inherent-safety requirements.

NIST Response Robot Test Methods

Standard Test Methods for Response Robots

<https://www.nist.gov/el/intelligent-systems-division-73500/standard-test-methods-response-robots>

Repeatable mobility, sensing, manipulation, endurance, and operator-proficiency tests.

ISO 10218-2:2025

Robotics - Safety Requirements - Industrial Robot Applications and Cells

<https://www.iso.org/standard/73934.html>

Current integration, commissioning, operation, maintenance, and disposal requirements.

Source currency rule: authorities, specifications, laws, provider services, hardware, protocols, standards status, and research evidence MUST be checked at assessment time. This publication records a 2026-07-24 source snapshot.

11.2 Revision History and Decision Register

Permanent identity, controlled change, and publication integrity

VERSION	DATE	STATE	SUMMARY
1.0.0-candidate	2026-07-24	Candidate	Permanent-publication edition; source refresh; expanded criteria, evidence, assurance, and lifecycle guidance.
Next review	2027-01-24	Scheduled	Review source currency, threat evolution, operating evidence, adoption feedback, and proposed revisions.

Publication decisions

- PERMANENT IDENTITY** The document ID remains stable across revisions; batch or production sequence metadata is not public identity.
- CHANGE CONTROL** Normative changes require rationale, impact analysis, affected-criterion mapping, and approval.
- SUPERSESION** A superseded edition remains traceable; current routes and catalogs identify the active edition.
- CORRECTION** Material errors require a recorded correction, affected-evidence analysis, and notification appropriate to impact.
- ARCHIVAL INTEGRITY** Published artifacts receive hashes, metadata, and a release manifest sufficient for independent verification.